Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model

economic models

Spatially heterogeneous IBM

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yuri Kondratiev

The University of Reading SFB-701 and BiBoS Bielefeld University

AGENDA

1. INTRODUCTION: INDIVIDUAL BASED MODELS IN CONTINUUM

- 2. MATHEMATICAL FRAMEWORK
- 3. Glauber dynamics I: spectral gap
- 4. Glauber dynamics II: non-equilibrium case
- 5. IBM in spatial ecology
- 6. IBM in economics
- 7. MUTATION-SELECTION MODELS
- 8. Ecological processes in random environment
- 9. Concluding remarks and discussions

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

Introduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

MACRO and MICRO models

PDE AND SPDE

as macroscopic descriptions coming from microscopic models via, in particular,

scaling limits(e.g., for densities)

scaling of fluctuations
 (normal or abnormal, equilibrium or non-equilibrium)

- closure of (infinite linear) moments systems (leading to non-linear but finite systems of PDEs)

- hierarchical chains (BBGKY etc.)

- heuristic arguments

(e.g., chemotaxis, porous media, mathematical finance,)

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

Introduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with establishment Dieckmann-Law model Competition in

economic models

MACRO and MICRO models

Some qualitative predictions based on the use of PDE and SPDE

may be considered as approximations (in a sense) to possible behaviors of microscopic systems,

which are mathematical caricatures of real world models, which are

"All models are caricatures of reality." Mark Kac

 $MICRO \Rightarrow MACRO ?$

 $\label{eq:MACRO} \ensuremath{\textup{MACRO}}\xspace \Rightarrow \ensuremath{\textup{MICRO}}\xspace ?$ Inverse problems, calibration, data assimilation, etc.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

Introduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Complex Systems: BIO sciences

S.Levin (Princeton)

"Complex Adaptive Systems: Exploring the Known, the Unknown and the Unknowable"

Bull. AMS, 2002:

- (1) diversity and individuality of components
- (2) localized interactions among components
- (3) the outcomes of interactions used for replication or enhancement of components

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

Introduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Complex Systems: SOCIO sciences

Philip Ball "Critical Mass" (2004): PHYSICS OF SOCIETY

Complexity theory seeks to understand how the order and stability arise from the interactions of many agents
We can make predictions about society even in the face of individual free will, and perhaps even illuminate the limits of that free will

- It is a science of humans collective behavior

<u>Thomas Hobbes</u>, "Leviaphan" (1651): WE MUST ASK NOT JUST **HOW** THINGS HAPPEN IN SOCIETY, BUT **WHY**. Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

Introduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in competition models

Statistical Mechanics for CS

R.Gomory:

The central problem is to develop an appropriate <u>statistical mechanics</u> that allows one to separate the <u>knowable unknown</u> from the truly <u>unknowable</u>. Such mechanics will have to deal with heterogeneous ensembles of interacting agents and with the continual refreshment of that ensemble by novel and unpredictable types. Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

Introduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with establishment Dieckmann-Law model Competition in

Statistical Mechanics for CS

The shift from Newtonian determinism to statistical science is what makes a physics of society possible.

Society itself is fundamentally a statistical phenomenon. Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

Introduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Statistical Mechanics for Physics

Equilibrium StatPhys

Non-equilibrium StatPhys

Hamiltonian dynamics

Stochastic dynamics (e.g., Glauber, Kawasaki, Metropolis, ...)

 $(\mathsf{Math.~StatPhys}) \subset (\mathsf{ID~Analysis})$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

Introduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Interacting Particle Systems

IPS as models in

condensed matter physics

chemical kinetics

population biology, ecology (individual based models=IBM) sociology, economics (agent based models=ABM)

Lattice (or) (and) (vs.) Continuous

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

Introduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development twith mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Individual Based Models

R. Law et al., *Ecology*, **84**(2003): IBM is a stochastic (Markov) process with events comprising birth, death, and movement.

Ecological models: Bolker/Pacala, 1997, ... Dickmann/Law, 2000, ...

Birch/Young, 2006 Kondratiev/Srorokhod, 2006 Meleard et al., 2007 Finkelshtein/Kondratiev/Kutovyi, 2007 Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

Introduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

We will consider

INDIVIDUAL BASED DYNAMICAL COMPETITION MODELS

rather than

COEXISTENCE REGULATION MECHANISMS, C.F., K/MINLOS/ZHIZHINA, '07 (ECONOMICS) K/KUNA/OHLERICH, '07 (GENETICS) Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

Introduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with establishment Dieckmann-Law model Competition in generatio models

Configuration spaces

- X = locally compact Polish space (e.g., $X = \mathbb{R}^d$ below) $\sigma(dx)$ intensity measure (= z dx)
- $\Gamma=\Gamma(X)\ni\gamma\text{, }\gamma\subset X$ locally finite configuration
- $F:\Gamma\to\mathbb{R}$ observables

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with establishment Dieckmann-Law model Competition in

General facts and notations

The configuration space:

 $\Gamma := \left\{ \gamma \subset \mathbb{R}^d | |\gamma \cap \Lambda| < \infty \text{ for all compact } \Lambda \subset \mathbb{R}^d \right\}.$

 $|\cdot|$ - cardinality of the set.

Vague topology $O(\Gamma)$:

the weakest topology s.t. all functions

$$\Gamma \ni \gamma \mapsto \sum_{x \in \gamma} f(x) \in \mathbb{R}$$

are continuous for all $f \in C_0(\mathbb{R}^d)$.

<u>Remark</u>: Γ is a Polish space.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models Dieckmann-Law model Competition in

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki Mynamics Free development with mortality Ecological models with establishment Dieckmann-Law model Competition in

Spatially heterogeneous IBM

n-point configuration space:

$$\Gamma^{(n)} := \left\{ \eta \subset \mathbb{R}^d \mid |\eta| = n \right\}, \quad n \in \mathbb{N}_0.$$

The space of finite configurations:

$$\Gamma_0 := \bigsqcup_{n \in \mathbb{N}_0} \Gamma^{(n)}.$$

 $\begin{array}{l} \underline{\textbf{Classes of functions}}: \ L^0(\Gamma_0): \quad \text{measurable functions on } \Gamma_0, \\ L^0_{\rm ls}(\Gamma_0): \quad \text{measurable with local support on } \Gamma_0 \\ G \in L^0_{\rm ls}(\Gamma_0) \Leftrightarrow \exists \ \Lambda \in \mathcal{B}_b(\mathbb{R}^d): \ G \upharpoonright_{\Gamma_0 \setminus \Gamma_\Lambda} = 0, \\ B_{\rm bs}(\Gamma_0): \quad \text{bounded with bounded support on } \Gamma_0 \\ G \in B_{\rm bs}(\Gamma_0) \Leftrightarrow \text{ bounded } \& \ \exists N \in \mathbb{N}, \exists \ \Lambda \in \mathcal{B}_b(\mathbb{R}^d): \end{array}$

$$G \upharpoonright_{\Gamma_0 \setminus \bigsqcup_{n=0}^N \Gamma_\Lambda^{(n)}} = 0$$

Cylinder functions on Γ :

 $\mathcal{F}L^0(\Gamma)$: $G \in L^0(\Gamma)$, s.t. for some $\Lambda \in \mathcal{B}_b(\mathbb{R}^d)$.

$$F(\gamma) = F(\gamma_{\Lambda}).$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

K-transform

Combinatorial Fourier transform (Lenard; Kondratiev/ Kuna):

$$KG(\gamma) := \sum_{\xi \Subset \gamma} G(\xi),$$

$$\gamma \in \Gamma, \ G \in L^0_{\mathrm{ls}}(\Gamma_0);$$

$$K^{-1}F(\eta) := \sum_{\xi \subset \eta} (-1)^{|\eta \setminus \xi|} F(\xi),$$

$$\eta \in \Gamma_0, \ F \in \mathcal{F}L^0(\Gamma).$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Spatially beterogeneous IBM

Convolution (Kondratiev/Kuna):

$$(G_1 \star G_2)(\eta) := \sum_{(\xi_1, \xi_2, \xi_3) \in \mathcal{P}^3_{\emptyset}(\eta)} G_1(\xi_1 \cup \xi_2) G_2(\xi_2 \cup \xi_3),$$

with property

$$K(G_1 \star G_2) = KG_1 \cdot KG_2,$$

$$G_1, G_2 \in L^0_{ls}(\Gamma_0).$$

Correlation measure

$$\mathcal{M}_{fm}^1(\Gamma) = \underline{\text{probability measures}}$$
 with finite local moments.
 $\mathcal{M}_{lf}(\Gamma_0) = \underline{\text{locally finite measures}}$ on Γ_0 .

One can define

$$\begin{split} K^* &: \mathcal{M}^1_{\mathrm{fm}}(\Gamma) \to \mathcal{M}_{\mathrm{lf}}(\Gamma_0) : \\ \forall \mu \in \mathcal{M}^1_{\mathrm{fm}}(\Gamma), \ G \in \mathcal{B}_{\mathrm{bs}}(\Gamma_0) \\ & \int_{\Gamma} KG(\gamma) \mu(d\gamma) = \int_{\Gamma_0} G(\eta) \ (K^*\mu)(d\eta). \\ \rho_\mu &:= K^*\mu \end{split}$$

is called the correlation measure.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model

Theorem

Let $\mu \in \mathcal{M}^1_{\mathrm{fm}}(\Gamma)$ be given. For any $G \in L^1(\Gamma_0, \rho_\mu)$ we define

$$KG(\gamma) := \sum_{\eta \Subset \gamma} G(\eta),$$

where the later series is μ -a.s. absolutely convergent. Furthermore, we have $KG \in L^1(\Gamma, \mu)$,

$$\int_{\Gamma_0} G(\eta) \, \rho_\mu(d\eta) = \int_{\Gamma} (KG)(\gamma) \, \mu(d\gamma).$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with establishment Dieckmann-Law model Competition in

Lebesgue-Poisson measure

 $\sigma = \text{Lebesgue measure on } (\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d)).$ For any $n \in \mathbb{N}$ measure $\sigma^{\otimes n}$ can be considered on $\widetilde{(\mathbb{R}^d)^n}$.

 $\begin{aligned} \sigma^{(n)} &= \text{ projection on } \Gamma^{(n)}. \\ \text{The Lebesgue-Poisson measure } \lambda_z \text{, } z > 0 \text{ on } \Gamma_0: \end{aligned}$

$$\lambda_z := \sum_{n=0}^{\infty} \frac{z^n}{n!} \sigma^{(n)}.$$

The restriction of λ_z to Γ_{Λ} we also denote by λ_z .

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Poisson measure

The **Poisson measure** π_z on $(\Gamma, \mathcal{B}(\Gamma))$ is given as the projective limit of the family of measures $\{\pi_z^{\Lambda}\}_{\Lambda \in \mathcal{B}_b(\mathbb{R}^d)}$, where π_z^{Λ} is the measure on Γ_{Λ} defined by

$$\pi_z^{\Lambda} := e^{-z\sigma(\Lambda)}\lambda_z$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

ree growth model Contact model in Sontinuum CM with Kawasaki Yimamics Free development Cological models with competition Cological models with establishment Dieckmann-Law model Competition in conder

Correlation functions

A measure $\mu \in \mathcal{M}^1_{\mathrm{fm}}(\Gamma)$ is called

locally absolutely continuous

w.r.t. π_z iff $\mu_\Lambda := \mu \circ p_\Lambda^{-1}$

is absolutely continuous with respect to $\pi_z^{\Lambda} = \pi_z \circ p_{\Lambda}^{-1}$ for all $\Lambda \in \mathcal{B}_b(\mathbb{R}^d)$.

In this case $\rho_{\mu} := K^* \mu$ is absolutely continuous w.r.t λ_z .

$$k_{\mu}(\eta) := \frac{d\rho_{\mu}}{d\lambda_z}(\eta), \ \eta \in \Gamma_0.$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with establishment Dieckmann-Law model Competition in

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Spatially heterogeneous IBM

$$k_{\mu}^{(n)} : (\mathbb{R}^d)^n \longrightarrow \mathbb{R}^+$$
$$k_{\mu}^{(n)}(x_1, \dots, x_n) :=$$

$$k_{\mu}(\{x_1,\ldots,x_n\})$$

correlation functions.

Definition

A measure $\rho \in \mathcal{M}_{lf}(\Gamma_0)$ is called positive definite if

$$\int_{\Gamma_0} (G \star \overline{G})(\eta) \rho(d\eta) \ge 0, \quad \forall G \in B_{bs}(\Gamma_0),$$

where \overline{G} is a complex conjugate of G. The measure ρ is called normalized iff $\rho(\{\emptyset\}) = 1$.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in Contact model in Continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

Introductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with establishment Dieckmann-Law model Competition in economic models

Spatially heterogeneous IBM

Theorem (Kondratiev/Kuna)

Let $\rho \in \mathcal{M}_{lf}(\Gamma_0)$ be given. Assume that ρ is positive definite, normalized and that for each bounded open $\Lambda \subset \mathbb{R}^d$, for every C > 0 there exists $D_{\Lambda, C} > 0$ s.t.

 $\rho(\Gamma_{\Lambda}^n) \le D_{\Lambda, C} C^n, \quad n \in \mathbb{N}_0.$

Then there exists a unique measure $\mu \in \mathcal{M}^1_{fm}(\Gamma)$ with $\rho = K^*\mu$.

Remark: A sufficient condition for the bound in the theorem:

 $\rho(\Gamma_{\Lambda}^{(n)}) \le (n!)^{-\varepsilon_{\Lambda}} (C_{\Lambda})^{n}.$

BAD generators

Birth-and-death processes in continuum

$$(LF)(\gamma) = \sum_{x \in \gamma} d(x, \gamma \setminus x) [F(\gamma \setminus x) - F(\gamma)] + \int_X b(x, \gamma) [F(\gamma \cup x) - F(\gamma)] dx$$

BIO (ecology) processes are specified by:

$$\begin{split} b(x,\gamma) &= \sum_{y \in \gamma} B_y(x,\gamma) \\ b(x,\emptyset) &= 0 \end{split}$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Existence problem

K/Lytvynov K/Lytvynov/Röckner Construction forms K/Kutoviy/Zhizhina K/Kutoviy/Minlos Holley/Stroock Ferrari/ Garcia K/Skorokhod Garcia/Kurtz Particular classes Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki Aynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Correlation equations

(= moment equations = hierarchical equations)

 $\mu_0 = initial distribution$

 $X_t^{\mu_0} \in \Gamma$ Markov process with initial distribution μ_0

 $\mu_t \in \mathcal{M}^1(\Gamma)$ distribution at time t > 0

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Correlation functions

$$\begin{aligned} f^{(n)}(x_1,\ldots,x_n) \text{ symmetric function } & \text{ on } X^n, \\ \gamma = \{x_1,x_2,\ldots\} \subset X \end{aligned}$$

$$\int_{\Gamma} \sum_{\{x_{i_1}, \dots, x_{i_n}\} \subset \gamma} f^{(n)}(x_{i_1}, \dots, x_{i_n}) d\mu(\gamma)$$

= $\frac{1}{n!} \int_{X^n} f^{(n)}(y_1, \dots, y_n) k^{(n)}_{\mu}(y_1, \dots, y_n) d\sigma(y_1) \cdots d\sigma(y_n)$

$$\begin{split} \mu &\rightleftarrows (k_{\mu}^{(n)})_{n=0}^{\infty} \\ \text{Lenard} \\ \text{K/Kuna} \\ \text{Berezansky/K/Kuna/Lytvynov} \end{split}$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in Contact model in Continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Correlation functions dynamics

In components:

$$\frac{\partial k_t^{(n)}}{\partial t} = (L_{CF}k_t)^{(n)}, n \ge 0$$

$$\frac{\partial k_t}{\partial t} = L_{CF} k_t$$

 L_{CF} : CF evolution generator

General theory of CF generators for BAD processes and several particular models: [Finkelstein/K/Oliveira '07]

Compare: BBGKY-hierarchy etc.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematical Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Spatial birth-and-death processes

We consider a Markov pre-generator on Γ , the action of which is given by

$$(LF)(\gamma) := (L_{b,d}F)(\gamma) =$$
$$= \sum_{x \in \gamma} d(x, \gamma \setminus x) D_x^- F(\gamma) + \int_{\mathbb{R}^d} b(x, \gamma) D_x^+ F(\gamma) dx,$$

$$D_x^- F(\gamma) = F(\gamma \setminus x) - F(\gamma),$$

 $D_x^+F(\gamma) = F(\gamma \cup x) - F(\gamma).$ Our systems are <u>defined</u> via stochastic dynamics. Symmetrizing measures? Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematic Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models Dieckmann-Law model Competition in

A Gibbs measure

$$\mu \in \mathcal{G}(\beta, z)$$

is reversible w.r.t. the stationary Markov process associated with the generator L in $L^2(\Gamma, \mu)$ (i.e. L is symmetric in $L^2(\Gamma, \mu)$) iff:

$$b(x, \gamma) = ze^{-\beta E(x, \gamma)}d(x, \gamma),$$

(detailed balance condition)

where $E(x, \gamma)$ is the relative energy of interaction between a particle located at x and the configuration γ :

$$E(x, \gamma) := \sum_{y \in \gamma} \phi(x - y)$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in geogenetic models

Gibbs measures

A measure $\mu \in \mathcal{M}^1(\Gamma)$ is called a Gibbs measure iff

$$\int_{\Gamma}\sum_{x\in\gamma}F(\gamma,\,x)\mu(d\gamma)=$$

$$= \int_{\Gamma} \mu(d\gamma) \int_{\mathbb{R}^d} z dx \exp\left[-\beta E(x,\,\gamma)\right] F(\gamma \cup x,\,x)$$

for any measurable function

$$F: \Gamma \times \mathbb{R}^d \to [0, +\infty).$$

 $\mathcal{G}(z,\beta) =$ all (grand canonical) Gibbs measures.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Glauber dynamics in continuum

Bertini/Cancrini/Cesi '02 (finite volume systems)

$$b(x, \gamma) = ze^{-\beta E(x, \gamma)}, \quad d(x, \gamma) = 1$$

[Kondratiev/Lytvynov,'03]:

under general conditions on the potential ϕ and the parameters β , z there exists a Markov process on Γ with the stationary measure $\mu \in \mathcal{G}(z, \beta)$.

The corresponding Markov generator L has form:

$$\begin{split} (LF)(\gamma) &= \sum_{x \in \gamma} \left(F(\gamma \setminus x) - F(\gamma) \right) \\ &+ z \int_{\mathbb{R}^d} \exp(-\beta E(x,\gamma)) (F(\gamma \cup x) - F(\gamma)) dx \end{split}$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

economic models

Spatially heterogeneous IBM

We will discuss properties of the operator

$$H = -L \ge 0$$

in $L^2(\Gamma,\mu)$ for

$$\mu \in \mathcal{G}(z,\beta)$$
We will say that the potential ϕ satisfies the integrability condition (I), if

$$\forall \beta > 0 \quad C(\beta) := \int |1 - e^{-\beta \phi(x)}| dx < \infty.$$

Theorem (Kondratiev/Lytvynov)

Suppose that the potential $\phi \geq 0$ and satisfies the integrability condition. For any $\mu \in \mathcal{G}(z,\beta)$ the operator H is essentially self-adjoint in $L^2(\Gamma,\mu)$.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in Contact model in Contact model Muth Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in competition models

Poincaré inequality for Glauber generator

$$(HF,F)_{L^{2}(\mu)} = \int_{\Gamma} \mu(d\gamma) \int_{\mathbb{R}^{d}} \gamma(dx) |(D_{x}^{-}F)(\gamma)|^{2}$$

Theorem (Poincaré Inequality)

Assume additionally

$$\delta := zC(\beta) < \frac{1}{e}$$

Then for the unique Gibbs measure $\mu \in \mathcal{G}(z,\beta)$ holds

$$(HF, F)_{L^{2}(\mu)} \ge (1 - \delta) \int_{\Gamma} (F(\gamma) - \langle F \rangle_{\mu})^{2} d\mu(\gamma),$$

for all $F \in D(H)$.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Spatially heterogeneous IBM

Remark: all known proofs Bertini/Cancrini/Cesi 2002 (finite volume) Wu 2003 (finite volume) Kondratiev/Lytvynov 2003 Kondratiev/Minlos/Zhizhina 2004 (+ one-particle subspaces etc.) use the condition $\phi \ge 0$.

Yu. Kondratiev

ntroduction

Mathematic: Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Spatially heterogeneous IBM

Definition (IbP formula)

The function $r: X \times \Gamma \longrightarrow \mathbb{R}_+$ which fulfills

$$\int_{\Gamma} \mu(d\gamma) \sum_{x \in \gamma} f(x, \gamma \setminus x) = \int_{X} \nu(dx) \int_{\Gamma} \mu(d\gamma) r(x, \gamma) f(x, \gamma)$$

for all measurable functions $f: X \times \Gamma \to \mathbb{R}_+$ is called Papangelou intensity (PI) of a measure μ on $(\Gamma, \mathcal{B}(\Gamma))$.

Glauber dynamics of continuous particle systems

Consider the Dirichlet form of the Glauber dynamics on $L^2(\Gamma,\mu)$, where $\mathcal{E}(\Gamma,\Gamma)$.

$$\int_{\Gamma} \mu(d\gamma) \int_{\mathbb{R}^d} \gamma(dx) (D_x^- F)(\gamma) (D_x^- G)(\gamma)$$

$$\begin{split} D_x^- F(\gamma) &= F(\gamma \setminus x) - F(\gamma) \\ D_x^+ F(\gamma) &= F(\gamma \cup x) - F(\gamma). \end{split}$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

ree growth model in contact model in continuum CM with Kawasaki Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

economic models

heterogeneous IBM

The bilinear form ${\mathcal E}$ is closable on $L^2(\Gamma,\mu)$ and its closure is a Dirichlet form. The generator (-L,D(L)) of the form $({\mathcal E},D({\mathcal E}))$ is given by

$$(LF)(\gamma) = \sum_{x \in \gamma} (F(\gamma \setminus x) - F(\gamma))$$
$$+ \int_{\mathbb{R}^d} r(x, \gamma) (F(\gamma \cup x) - F(\gamma)) dx$$

Theorem

Under mild conditions on Papangelou intensity, there exists a Hunt process

 $\mathbf{M} = (\mathbf{\Omega}, \mathbf{F}, (\mathbf{F}_t)_{t \ge 0}, (\mathbf{\Theta}_t)_{t \ge 0}, (\mathbf{X}(t))_{t \ge 0}, (\mathbf{P}_{\gamma})_{\gamma \in \Gamma})$

on Γ which is properly associated with $(\mathcal{E}, D(\mathcal{E}))$. **M** is up to μ -equivalence unique. In particular, **M** is μ -symmetric and has μ as an invariant measure. Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap Glauber dynamics for

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

"Carré du champ" and "Carré du champ itéré"

Define the "carré du champ" corresponding to L as

$$\Box(F,G) := \frac{1}{2}(L(FG) - FLG - GLF).$$

$$\Box(F,G) = \frac{1}{2} \sum_{x \in \gamma} D_x^- F(\gamma) D_x^- G(\gamma) + \frac{1}{2} \int r(x,\gamma) D_x^+ F(\gamma) D_x^+ G(\gamma) dx.$$

Iterating the definition of "carré du champ" introduce "carré du champ itéré" \Box_2

$$2\Box_2(F,F) := L\Box(F,F) - 2\Box(F,LF).$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with establishment Dieckmann-Law model Competition in economic models

Coercivity identity

Through direct calculations we obtain

$$\mathcal{E}(F,F) = \int_{\Gamma} \Box(F,F)(\gamma)\mu(d\gamma).$$
$$\int_{\Gamma} (LF)^{2}(\gamma)\mu(d\gamma) = \int_{\Gamma} \Box_{2}(F,F)(\gamma)\mu(d\gamma)$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in Continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

economic models

Theorem

$$\begin{split} \int_{\Gamma} (LF)^2(\gamma)\mu(d\gamma) &= \int_{\Gamma} \Box_2(F,F)(\gamma)\mu(d\gamma) \\ &= \int_{\Gamma} \Box(F,F)(\gamma)\mu(d\gamma) + \int_{\Gamma} \sum_{x\in\gamma} \sum_{y\in\gamma\setminus x} \left(D_x^- D_y^- F\right)^2(\gamma)\mu(d\gamma) \\ &+ \int_{\Gamma} \int_{\mathbb{R}^d} r(x,\gamma) \int_{\mathbb{R}^d} D_x^+ r(y,\cdot)(\gamma) D_y^+ F(\gamma) D_x^+ F(\gamma) dy dx \mu(d\gamma) \end{split}$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Sufficient condition for spectral gap

The Poincaré inequality

$$c\int \left(f-\int fd\mu\right)^2 d\mu \leq \mathcal{E}(f,f).$$

The largest possible c gives the spectral gap of the generator H. Coercivity inequality: for a nonnegative (essentially self-adjoint) operator H (generator of \mathcal{E})

$$\int_{\Gamma} (HF)^2(\gamma)\mu(d\gamma) \ge c\mathcal{E}(F,F), \quad c > 0$$

If fulfilled, then (0, c) does not belong to the spectrum of H.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with establishment Dieckmann-Law model Competition in economic models

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Spatially heterogeneous IBM

Rewriting in terms of the "carré du champ" and \Box_2

$$\int_{\Gamma} \Box_2(F,F)(\gamma)\mu(d\gamma) \ge c \int_{\Gamma} \Box(F,F)(\gamma)\mu(d\gamma).$$

The following inequality is sufficient:

$$(1-c) \int_{\Gamma} \int_{\mathbb{R}^d} r(x,\gamma) (D_x^+ F)^2(\gamma) dx \mu(d\gamma) + \int_{\Gamma} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} r(x,\gamma) D_x^+ r(y,\cdot)(\gamma) D_y^+ F(\gamma) D_x^+ F(\gamma) dy dx \mu(d\gamma) \ge 0$$

Definition

A (generalized) function $B : \mathbb{R}^d \times \mathbb{R}^d \longrightarrow \mathbb{C}$ is called a positive definite kernel if for all $\psi \in C_0^{\infty}(\mathbb{R}^d)$ holds

$$\int_{\mathbb{R}^d} \int_{\mathbb{R}^d} B(x, y) \psi(x) \overline{\psi(y)} dx dy (= \langle B, \psi \otimes \overline{\psi} \rangle) \ge 0.$$

Theorem

If for μ -a.a. γ the kernel

$$r(x,\gamma)(r(y,\gamma)-r(y,\gamma\cup x))+(1-c)\sqrt{r(x,\gamma)}\sqrt{r(y,\gamma)}\delta(x-y)$$

is positive definite then the coercivity inequality holds for H with constant c.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in Contact model in Continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Coercivity inequality for Gibbs measures

Theorem

Let μ be a Gibbs measure for a pair potential ϕ and activity z. If for each fixed γ the kernel

$$e^{-\frac{1}{2}E(x,\gamma)}e^{-\frac{1}{2}E(y,\gamma)}z(1-e^{-\phi(x-y)}) + (1-c)\delta(x-y)$$

is positive definite then the coercivity inequality holds for H with constant c.

The condition above with $\boldsymbol{c}=1$ holds if

$$\int_{\mathbb{R}^d} \int_{\mathbb{R}^d} (1 - e^{-\phi(x-y)})\psi(y)\overline{\psi}(x)dxdy \ge 0$$
(1)

for all $\psi \in C_0(\mathbb{R}^d)$.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Definition

A measurable function $u:\mathbb{R}^d\longrightarrow\mathbb{C}$ is called positive definite if for all $\psi\in C_0(\mathbb{R}^d)$

$$\int_{\mathbb{R}^d} \int_{\mathbb{R}^d} u(x-y)\psi(x)\overline{\psi(y)}dxdy \ge 0.$$

Condition (1) means that $x \mapsto 1 - e^{-\phi(x)}$ is a positive definite function.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in competition in

Examples

 $\begin{array}{c|c|c|c|c|c|c|c|c|}\hline \phi(x) & f(x) & \mathsf{Parameters} \\ \hline \hline -\ln(1-e^{-tx^2}\cos(ax)), & e^{-tx^2}\cos(ax), & t>0, a\in\mathbb{R} \\ -\ln(1-e^{-t|x|}\cos(ax)), & e^{-t|x|}\cos(ax), & t>0, a\in\mathbb{R} \\ \hline -\ln\left(1-\frac{\cos(ax)}{1+\sigma^2x^2}\right), & \frac{1}{1+\sigma^2x^2}\cos(ax), & \sigma>0, a\in\mathbb{R} \\ \hline \mathsf{In} \text{ all examples above one can change } \cos(ax) \text{ to } \frac{\sin(ax)}{ax}. \\ & \mathsf{We \ can \ also \ give \ d-dimensional \ examples.} \end{array}$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Theorem

Let f be a continuous positive definite function which is (R). Define $\phi := -\ln(1 - f)$. Then ϕ is (SS) and (R). For every tempered Gibbs measure μ with potential ϕ the generator Hfulfills the coercivity inequality for c = 1.

Now we consider which properties a potential necessarily has which fulfills condition (1).

Theorem

Let ϕ be a potential which fulfills condition (1) and is (S), (R), and continuous. Then it is of the form $\phi := -\ln(1-f)$ and hence also (SS). Furthermore, ϕ is integrable, itself positive definite in the sense of generalized functions, and

$$\lim_{x \to 0} \frac{\phi(x)}{-2\ln(x)} \le 1.$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in Contact model in Continuum CM with Kawasaki dynamics Free development with mortality Ecological models with establishment Dieckmann-Law model Competition in economic models

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Spatially heterogeneous IBM

Lemma

Let $f : \mathbb{R} \to [0,1]$, $f \in C^2(\mathbb{R})$, even function, decreasing and convex on \mathbb{R}_+ . Denote $\phi(x) = -\ln(1 - f(x))$. Then $f_\beta = 1 - e^{-\beta\phi(x)}$ is also positive definite for all β such that $0 \le \beta \le 1$.

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Spatially heterogeneous IBM

In the <i>d</i> -dimensional case we can give following examples: $\phi(x) = -\ln(1 - f(x)).$	
f(x)	Parameters
$e^{-t x ^2}\cos(a\cdot x)$	$x \in \mathbb{R}^d, t > 0, a \in \mathbb{R}^d$
$e^{-t x ^2} \prod_{j=1}^d \frac{\sin(a_j x_j)}{a_j x_j}$	$x \in \mathbb{R}^d, t > 0$
$(\frac{r}{ x })^{n/2} J_{n/2}(r x)$	$r \geq 0$, $n > 2d - 1$
$\frac{2^{n/2}\Gamma(\frac{n+1}{2})}{\sqrt{\pi}}\cdot\frac{t}{(x ^2+t^2)^{\frac{n+1}{2}}}$	t>0,n>d-1

where $J_{n/2}$ is the Bessel function of the first kind.

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Spatially heterogeneous IBM

 $\mathsf{Dirichlet} \ \mathsf{forms} \mapsto \mathsf{equilibrium} \ \mathsf{Markov} \ \mathsf{processes}$

Possible initial states: absolute continuous w.r.t. reversible measures

Non-equilibrium dynamics: general initial states

Problem: how far from equilibrium stochastic dynamics makes sense?

Mathematical formulation: admissible classes of initial measures

References: K/Kutoviy/Zhizhina, J.Math.Phys., 2006 K/Kutoviy/Minlos, J.Funct.Anal., 2008

General scheme of construction of non-equilibrium process

• Let $\rho: \Gamma_0 \to \mathbb{R}$ be arbitrary positive function. Denote

$$\mathcal{M}^{1}_{\rho}(\Gamma) := \left\{ \mu \in \mathcal{M}^{1}(\Gamma) \mid k_{\mu} \leq const \cdot \rho \right\}.$$

Let L be a Markov pre-generator defined on some set of functions F(Γ) given on the configuration space Γ.
 Comments:

$$\frac{\partial F_t}{\partial t} = LF_t, \quad (KE)$$

$$F_t = e^{tL}F_0 \quad (Markov \ semigroup)$$

$$\frac{\partial \mu_t}{\partial t} = L^*\mu_t, \quad (DKE = FPE)$$

$$\mu_t = e^{tL^*}\mu_0 \quad (state \ evolution)$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Dieckmann-Law model Competition in

Let

$$\hat{L} := K^{-1}LK$$

be a formal K- transform or symbol of the operator L (our starting object).

We consider

$$\hat{L}: D(\hat{L}) \subset \mathcal{L} \to \mathcal{L}$$

in a Banach space

$$\mathcal{L} := L^1(\Gamma_0, \rho \, d\lambda_1) = \bigoplus_{n=0}^{\infty} L^1\left(\Gamma^{(n)}, \, \rho^{(n)}\sigma^{(n)}\right).$$

Suppose that domain of this operator is such that it is closed and densely defined in \mathcal{L} .

Suppose that $(\hat{L}, D(\hat{L}))$ is a generator of a semigroup in \mathcal{L} :

$$\hat{L} \to \hat{U}_t, t \ge 0$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Spatially heterogeneous IBM

\blacktriangleright Introducing duality between Banach spaces ${\cal L}$ and

$$\mathcal{K}(\rho) := \left\{ k : \Gamma_0 \to \mathbb{R} \mid k \cdot \rho^{-1} \in L^{\infty}(\Gamma_0, \lambda_1) \right\} :$$
$$<< G, \ k >> :=$$
$$= \int_{\Gamma_0} G \cdot k d\lambda_1 = \int_{\Gamma_0} G \cdot \frac{k}{\rho} \cdot \rho d\lambda_1, \ G \in \mathcal{L},$$

we construct semigroup $\hat{U}_t^{\star}, t \geq 0$ on $\mathcal{K}(\rho)$.

• Suppose that function ρ in the definition of $\mathcal{K}(\rho)$ satisfies Ruelle-type bound. Let $k \in \mathcal{K}(\rho)$ is a correlation function (i.e. the corresponding correlation measure is normalized, positive definite) and let

$$k_t := \hat{U}_t^{\star} k, \ t \ge 0$$

denotes an evolution of function k.

Assume that for any $t \ge 0$, $k_t \in \mathcal{K}(\rho)$ is positive definite, normalized function.

Yu. Kondratiev

ntroduction

Mathematic Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Spatially heterogeneous IBM

By the main CF theorem one can easily construct a semigroup on \mathcal{M}_{o}^{1} :

 $\begin{aligned} k & \to & \mu, \\ k_t &= \hat{U}_t^{\star} k & \to & U_t^{\star} \mu, \ t \ge 0, \\ \mu_t &= U_t^{\star} \mu \in \mathcal{M}_{\rho}^1. \end{aligned}$

The existence of semigroup U_t^{\star} , $_{t\geq 0}$ on \mathcal{M}_{ρ}^1 implies the existence of process $(X_t^{\mu})_{t\geq 0}$ associated with generator L for any initial distribution $\mu \in \mathcal{M}_{\rho}^1$.

Spatial birth-and-death processes

We consider a Markov pre-generator on $\Gamma,$ the action of which is given by

$$(LF)(\gamma) := (L_{b,d}F)(\gamma) =$$
$$= \sum_{x \in \gamma} d(x, \gamma \setminus x) D_x^- F(\gamma) + \int_{\mathbb{R}^d} b(x, \gamma) D_x^+ F(\gamma) dx,$$

$$D_x^- F(\gamma) = F(\gamma \setminus x) - F(\gamma),$$

 $D_x^+ F(\gamma) = F(\gamma \cup x) - F(\gamma).$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematic Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

It is known that a Gibbs measure

$$\mu \in \mathcal{G}(eta, z)$$

is reversible w.r.t. the stationary Markov process associated with the generator L in $L^2(\Gamma, \mu)$ (i.e. L is symmetric in $L^2(\Gamma, \mu)$) iff:

$$b(x, \gamma) = z e^{-\beta E(x, \gamma)} d(x, \gamma),$$

where $E(x, \gamma)$ is the relative energy of interaction between a particle located at x and the configuration γ :

$$E(x, \gamma) := \sum_{y \in \gamma} \phi(x - y)$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki Anamics Free development with mortality Ecological models with establishment Dieckmann-Law model Competition in

Gibbs measures

A measure $\mu \in \mathcal{M}^1(\Gamma)$ is called a Gibbs measure iff

$$\int_{\Gamma}\sum_{x\in\gamma}F(\gamma,\,x)\mu(d\gamma)=$$

$$= \int_{\Gamma} \mu(d\gamma) \int_{\mathbb{R}^d} z dx \exp\left[-\beta E(x,\,\gamma)\right] F(\gamma \cup x,\,x)$$

for any measurable function

$$F: \Gamma \times \mathbb{R}^d \to [0, +\infty).$$

 $\mathcal{G}(z,\beta)$ = all Gibbs measures.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Glauber dynamics (G_{\pm})

Consider as above the case

$$b(x, \gamma) = ze^{-\beta E(x, \gamma)}, \quad d(x, \gamma) = 1.$$

The corresponding generator: $L^+ := L$.

Glauber dynamics (G_{-}) :

$$b(x, \gamma) = z, \quad d(x, \gamma) = e^{\beta E(x, \gamma)}.$$

The corresponding generator: L^- .

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

The symbol of Glauber generator on the space of finite configurations

<u>Potential</u>: $\phi : \mathbb{R}^d \to \mathbb{R} \cup \{+\infty\}$ Borel, even function. (I) Integrability: $\forall \beta > 0$

$$c(\beta) := \int_{\mathbb{R}^d} |1 - e^{-\beta \phi(x)}| dx < \infty.$$

(P) Positivity: $\phi(x) \ge 0$ for all $x \in \mathbb{R}^d$. The image of L under the K-transform has the following form:

$$(\widehat{L}G)(\eta) := (K^{-1}LKG)(\eta) = -|\eta|G(\eta) +$$
$$+z\sum_{\xi \subseteq \eta} \int_{\mathbb{R}^d} G(\xi \cup x) \prod_{y \in \eta \setminus \xi} (e^{-\beta\phi(x-y)} - 1)e^{-\beta E(x,\xi)} dx =$$
$$= (L_0G)(\eta) + z(L_1G)(\eta), \quad G \in B_{bs}(\Gamma_0).$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Non-equilibrium dynamics (G_+) . Construction of a semigroup.

 λ = Lebesgue-Poisson measure on Γ_0 with z = 1. For fixed C > 0 and $\beta > 0$, we consider operator \hat{L} in

$$\mathcal{L}_{C,\beta} := L^1(\Gamma_0, C^{|\eta|} e^{-\beta E(\eta)} d\lambda(\eta))$$

Let $\kappa := z > 0$ be the parameter of the considering model. Then

$$\widehat{L}G)(\eta) = (\widehat{L_{\kappa}}G)(\eta) = (L_0G)(\eta) + \kappa(L_1G)(\eta)$$
$$G \in D(L_1) = D(L_0) =$$
$$= \{G \in \mathcal{L}_{C,\beta} \mid |\eta| G(\eta) \in \mathcal{L}_{C,\beta} \}.$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

,

Free growth model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Yu. Kondratiev

ntroduction

Mathematic Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

(2)

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with establishment Dieckmann-Law model Competition in

Spatially

Theorem

For any C > 0, and for all κ , $\beta > 0$ which satisfy

 $\kappa \exp\left(C(\beta)C\right) < C,$

the operator $\widehat{L_{\kappa}}$ is a generator of a holomorphic semigroup in $\mathcal{L}_{C,\,\beta}.$

Construction of non-equilibrium Markov process

Fix any triple C, κ and β : $\kappa \exp(C(\beta)C) < C$.

 $\widehat{U_t}(C,\kappa,eta)$ be holomorphic semigroup generated by $\widehat{L_\kappa}$

$$\mathcal{K}_{C,\,\beta} := \left\{ k: \Gamma_0 \to \mathbb{R}_+ \mid \, k(\cdot) \, C^{-|\cdot|} e^{\beta E(\cdot)} \in L^{\infty}(\Gamma_0,\lambda) \right\}$$

the space for possible correlation functions.

Duality between quasi-observables $G \in \mathcal{L}_{C,\beta}$ and functions $k \in \mathcal{K}_{C,\beta}$:

$$\langle \langle G, \, k \rangle \rangle := \langle G, \, k \rangle_{L^2(\Gamma_0, \, \lambda)} \, .$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with actuality Ecological models with establishment Dieckmann-Law model

Competition in economic models

Spatially heterogeneous IBM

Remark: 1.
$$\langle G, k \rangle_{L^2(\Gamma_0, \lambda)} =$$

$$= \int_{\Gamma_0} G(\eta) C^{|\eta|} e^{-\beta E(\eta)} k(\eta) C^{-|\eta|} e^{\beta E(\eta)} d\lambda(\eta) < \infty.$$
2. $k(\cdot) C^{-|\cdot|} e^{\beta E(\cdot)} \in L^{\infty}(\Gamma_0, \lambda)$ implies
 $k(\eta) \leq const C^{|\eta|} e^{-\beta E(\eta)}.$

Duality determines semigroup on $\mathcal{K}_{C,\beta}$:

$$\widehat{U_t}(C,\kappa,\beta)\longleftrightarrow \widehat{U_t^\star}(C,\kappa,\beta).$$

Lemma

if

Let positive constants C, κ and β which satisfy

 $\kappa \exp\left(C(\beta)C\right) < C$

be arbitrary and fixed. The semigroup $\widehat{U}_t^*(C,\kappa,\beta)$ on $\mathcal{K}_{C,\beta}$ preserves positive definiteness, i.e.

$$\left\langle \left\langle G \star G, \, \widehat{U_t^\star}(C, \kappa, \beta) k \right\rangle \right\rangle \ge 0, \quad \forall \, G \in B_{bs}(\Gamma_0)$$
$$\left\langle \left\langle G \star G, \, k \right\rangle \right\rangle \ge 0,$$

for any $G \in B_{bs}(\Gamma_0)$.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Let $\mathcal{M}_{C,\beta}$ - the set of all probability measures on Γ , locally absolutely continuous with respect to Poisson measure, with locally finite moments, whose correlation functions satisfy bound

$$k(\eta) \le \operatorname{const} C^{|\eta|} e^{-\beta E(\eta)}$$

Theorem

Suppose that conditions (I) and (P) are satisfied. For any triple of positive constants C, κ and β which satisfy

 $\kappa \exp\left(C(\beta)C\right) < C$

and any $\mu \in \mathcal{M}_{C,\beta}$ there exists Markov process $X_t^{\mu} \in \Gamma$ with initial distribution μ associated with generator L_{κ} .

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematic Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in contact model in continuum CM with Kawasaki dynamics Free development event development tith competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Glauber dynamics G_{-}

$$b(x, \gamma) = z, \quad d(x, \gamma) = e^{\beta E(x, \gamma)}$$

For arbitrary and fixed C > 0 we consider \hat{L}^- in

$$\mathcal{L}_C := L_1(\Gamma_0, C^{|\eta|} d\lambda(\eta)).$$

For the potential ϕ assume:

(S) Stability: $\exists B \geq 0$, s.t. $\forall \eta \in \Gamma_0$

$$E(\eta) := \sum_{\{x, y\} \subset \eta} \phi(x - y) \ge -B|\eta|,$$

(SI) Strong Integrability:

$$C_{st}(\beta) := \int_{\mathbb{R}^d} |1 - e^{\beta \phi(x)}| dx < \infty$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBN

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in
Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematic Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Spatially heterogeneous IBM

Theorem

For any C > 0, and for all κ , $\beta > 0$ which satisfy

$$e^{C_{st}(\beta)} + \kappa e^{2B\beta}C^{-1} < 2$$

the operator $\widehat{L^{-}}$ is a generator of a holomorphic semigroup in \mathcal{L}_{C} .

Stochastic growth

BIO: independent growth (plants) Dispersion kernel:

 $a^+(x-y) dx$ $0 \le a^+ \in L^1(\mathbb{R}^d)$ even.

Generator:

 $(L_{IG}F)(\gamma) = \sum_{y \in \gamma} \int_{\mathbb{R}^d} a^+ (x - y) [F(\gamma \cup x) - F(\gamma)] dx$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model

Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

SOCIO-ECO: free development=independent birth (creation by an outer free will)

 $(L_{IB}F)(\gamma) = z \int_{\mathbb{R}^d} (F(\gamma \cup x) - F(\gamma)) dx$

GENETICS: generalized mutation models Evans/Steinsalz/Wichtner, 2005 Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model

Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models Dieckmann-Law model Competition in economic models

Density of population

Independent Growth:

$$k_t(x)\sim Ce^{\lambda t}$$
, $t
ightarrow\infty$

Independent Birth:

$$k_t(x) \sim Ct, t \to \infty$$

Free Evolution Models

Problem: to analyze stochastic evolution models in the presence of global regulations and local competitions

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model

Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models Dieckmann-Law model Competition in economic models

IG with mortality = Contact Model

Generator:

$$(LF)(\gamma) = \sum_{x \in \gamma} m[F(\gamma \setminus x) - F(\gamma)] + \sum_{y \in \gamma} \int_{\mathbb{R}^d} a^+ (x - y)[F(\gamma \cup x) - F(\gamma)] \, dx$$

m =global mortality intensity

Existence of Markov process:

[K/Skorokhod, 06] finite range a^+ [Finkelstein/K/Skorokhod, 07] general case a^+ Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model

Contact model in continuum

dynamics Free development

with mortality

with competition

with establishment

model

competition in economic models

Correlation equations for CM

[K/Kutoviy/Pirogov, 07]

What can happen?

Take translation-invariant initial condition

$$\begin{split} k_t(x) &\equiv \rho_t. \\ \frac{\partial \rho_t}{\partial t} &= -(m - \langle a^+ \rangle)\rho_t \\ m &> \langle a^+ \rangle \Rightarrow \rho_t \to 0 \\ m &< \langle a^+ \rangle \Rightarrow \rho_t \to +\infty \\ m &= \langle a^+ \rangle \Rightarrow \rho_t \equiv \rho_0 \\ m &= \langle a^+ \rangle \text{ critical value of mortality} \end{split}$$

Possible invariant state: for $m = \langle a^+ \rangle$ $\boxed{m = m_{cr}}$ Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBN

Free growth model Contact model in

continuum

dynamics Free development

Ecological models

Ecological models with establishment

Dieckmann-Law model

Competition in economic models

CF time evolution

$$\frac{\partial k_t^{(n)}}{\partial t}(x_1,\ldots,x_n) =$$

$$-nmk_t^{(n)}(x_1,\ldots,x_n)+$$

$$\sum_{i=1}^{n} \left[\sum_{j \neq i} a^{+} (x_{i} - x_{j}) \right] k_{t}^{(n-1)}(x_{1}, \dots, \check{x}_{i}, \dots, x_{n}) +$$

$$\sum_{i=1}^{n} \int_{\mathbb{R}^d} a^+(x_i - y) k_t^{(n)}(x_1, \dots, x_{i-1}, y, x_{i+1}, \dots, x_n) \, dy$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model

Contact model in continuum

CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models

with establishment

model

economic models

Theorem

Let
$$k_0^{(n)} \leq C^n n!$$
, $n \geq 0$.
Then $k_t^{(n)}(x_1, \dots, x_n) \leq A^n (C+t)^n e^{n(-m)t} n!$.

Remark:

actually for a Poisson initial state and $x_1, ..., x_n$ inside a small ball

$$k_t^{(n)}(x_1,\ldots,x_n) \simeq C_t^n n!, \ t > 0, n \to \infty,$$

that means

STRONG CLUSTERING!

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum

CM with Kawasaki dynamics Free development with mortality Ecological models with competition

Ecological models with establishment

Dieckmann-Law model

Competition in economic models

Invariant measures

Let $d \geq 3$.

Stationary equation:

$$\frac{\partial k_t}{\partial t} = 0$$

Theorem

Assume
$$a^+$$
: $\int_{\mathbb{R}^d} |x|^2 a^+(x) dx < \infty$.
 $\forall \rho > 0 \exists !$ solution $(k^{(n),\rho})_{n=0}^{\infty}$ corresponding to a measure
 $\mu^{\rho} \in \mathcal{M}^1(\Gamma)$ with $k^{(1),\rho}(x) = \rho$.
We have $k^{(n),\rho}(x) \leq C(\rho)^n (n!)^2$, $n \geq 1$.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in

continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models

ieckmann-Law iodel

Competition in economic models

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBN

Free growth model Contact model in

contact model in continuum

dynamics

with mortality

with competition

with establishment

Dieckmann-Law model

economic models

Spatially heterogeneous IBM

For $d \leq 2 \ \mu^{\rho}$ does not exist!

The point:

$$\int_{|p| \le 1} \frac{dp}{\tilde{a}(0) - \tilde{a}(p)} < \infty$$

necessary condition for the existence of $k^{(2),\rho}(x,y)$.

CM + Kawasaki dynamics (plankton model)

K/Kutoviy/Struckmeier '08 Equilibrium state for CM needs $d \ge 3$. d = 2?

Consider a CM with a motion of individuals: take into account different time scales Generator in the bio-time scale:

$$(LF)(\gamma) = \sum_{x \in \gamma} \int_{\mathbb{R}^d} \varkappa (x - y) [F(\gamma \setminus x \cup y) - F(\gamma)] \, dy + (L_{\mathsf{CM}}F)(\gamma)$$
$$= ((L_{\mathsf{K}} + L_{\mathsf{CM}})F)(\gamma)$$
$$\boxed{L = L_{\mathsf{K}}(\varkappa) + L_{\mathsf{CM}}(m, a^+)}$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum

CM with Kawasaki dynamics

Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Critical value
$$m = \langle a^+ \rangle$$
.

Assume long tail jumps:

$$\int_{|p|\leq 1}\frac{1}{1-\tilde{\varkappa}(p)}\,dp<\infty$$

For example:

 $ilde{arkappa}(p)=e^{-|p|^{lpha}}$,

 $1 \le \alpha < 2$ (stable distributions)

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum

CM with Kawasaki dynamics

Free development with mortality

with competition

with establishment

Dieckmann-Law model

competition in economic models

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematic Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum

CM with Kawasaki dynamics

Free development with mortality

with competition Ecological models with establishment

Dieckmann-Law model

economic models

Spatially heterogeneous IBM

Theorem

 $\forall \rho > 0 \exists !$ invariant measure μ^{ρ} for CM with Kawasaki dynamics.

INTERPRETATION: super-diffusive stochastic dynamics of individuals in bio-time scale.

Independent birth with mortality

Surgailis process:

$$\begin{split} (LF)(\gamma) &= m \sum_{x \in \gamma} (F(\gamma \setminus x) - F(\gamma)) + \\ z \int_{\mathbb{R}^d} (F(\gamma \cup x) - F(\gamma)) dx \end{split}$$

Unique invariant measure is the Poisson measure on Γ with intensity \$z\$

 \overline{m}

ANY non-zero mortality stabilizes the system!

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics

Free development with mortality

Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models

Bolker-Pacala model

(= CM + density dependent mortality)

$$L = L_{CM} + L(a^{-})$$

$$(LF)(\gamma) = \sum_{x \in \gamma} \left(m + \sum_{x' \in \gamma \setminus x} a^{-}(x - x') \right) [F(\gamma \setminus x) - F(\gamma)] + \sum_{y \in \gamma} \int_{\mathbb{R}^d} a^{+}(x - y) [F(\gamma \cup x) - F(\gamma)] dx$$

 $\begin{array}{l} a^+(x-y) - \text{dispersion kernel} \\ a^-(x-y) - \text{competition kernel} \\ 0 \leq a^\pm \in L^1(\mathbb{R}^d) \end{array}$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality

Ecological models with competition

Ecological models with establishment Dieckmann-Law model Competition in economic models

CF evolution

[Finkelshtein/K/Kutoviy, 2007] Generator on correlation functions:

$$(L_{CF}k)(\eta) = -k(\eta) \left[m|\eta| + \varkappa^{-} E^{a^{-}}(\eta) \right] - \varkappa^{-} \int_{\mathbb{R}^{d}} \sum_{y \in \eta} a^{-} (x-y)k(\eta \cup x)dx + \varkappa^{+} \sum_{x \in \eta} k(\eta \setminus x) \sum_{y \in \eta \setminus x} a^{+} (x-y) + \varkappa^{+} \int_{\mathbb{R}^{d}} \sum_{x \in \eta} a^{+} (x-y)k(\eta \setminus x \cup y)dy.$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality

Ecological models with competition

Ecological models with establishment Dieckmann-Law model Competition in economic models

May the competition mechanism lead to

THE "REGULARLY DISTRIBUTED" IN SPACE POPULATION

with bounded in time density?

Necessary condition: big enough mortality m (that follows from an accretivity assumption)

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality

Ecological models with competition

Ecological models with establishment Dieckmann-Law model Competition in economic models

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality

Ecological models with competition

Ecological models with establishment Dieckmann-Law model Competition in economic models

Spatially heterogeneous IBM

Competition assumptions (CA):

 $\exists C > 0: \ a^+(x) \le Ca^-(x)$

 $m > C\langle a^-
angle + \langle a^+
angle$

that means strong enough competition and mortality

Theorem

Let (CA) fulfilled. For any initial CF s.t.

$$k_0^{(n)} \le C^n, n \in \mathbb{N}$$

there exists the unique solution of the CF equation $k_t^{(n)}, t \ge 0, n \in \mathbb{N}$, satisfying the same bound

This gives a sub-Poissonian bound, i.e., the strong enough competition

destroys the clustering in CM!

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality

Ecological models with competition

Ecological models with establishment Dieckmann-Law model Competition in economic models

CM with establishment

$$\begin{split} & [\mathsf{Finkelshtein}/\mathsf{K}.\ 2007]\\ & a^+(x-y) \ \longrightarrow \ a^+(x-y)e^{-E^{\phi}(x,\gamma)}\\ & e^{-E^{\phi}(x,\gamma)}=e(x,\gamma) \text{ establishment rate}\\ & E^{\phi}(x,\gamma)=\sum_{x'\in\gamma}\phi(x-x')\\ & \text{competition for survival} \end{split}$$

Bolker-Pacala establishment rate

$$e(x,\gamma) = \frac{1}{1 + E^{\phi}(x,\gamma)}$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models

Ecological models with competition

Ecological models with establishment

Dieckmann-Law model Competition in economic models

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality

Ecological models with competition

Ecological models with establishment

Dieckmann-Law model Competition in economic models

Spatially heterogeneous IBM

Generator

$$(LF)(\gamma) = \sum_{x \in \gamma} m[F(\gamma \setminus x) - F(\gamma)] + \sum_{y \in \gamma} \int_{\mathbb{R}^d} a^+ (x - y) e(x, \gamma) [F(\gamma \cup x) - F(\gamma)] dx$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality

with competition

Ecological models with establishment

Dieckmann-Law model Competition in economic models

Spatially heterogeneous IBM

 $\frac{\text{Stability condition:}}{L=L(m,a^+,\phi)} \ m>0, \ \exists \beta>0: a^+(x)\leq \beta \phi(x)$

Theorem

Under stability condition there exists a unique Markov process on Γ for $L(m, a^+, \phi)$ (for certain class of initial configurations).

Proof is based on a delicate use of

a [Garcia/Kurtz, 2006] existence result

Correlation functions in CM with establishment

Time evolution of CF

Theorem (K/Finkelstein '07)

Assume stability condition is true and initial CFs satisfy a sub-Poisson bound $k_0^{(n)} \leq C^n, n \geq 1$. Then there exists $C_1 > 0$ s.t. for the time dependent CFs holds

$$k_t^{(n)} \le C_1^n, n \ge 1.$$

Remark:

The establishment mechanism is more effective comparing with density dependent mortality:

we do not need to have a big enough mortality to organize control over time-space behavior of the population Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models

Ecological models with establishment

Dieckmann-Law model Competition in economic models

Density dependent fecundity

$$b(x,\gamma) = \sum_{y \in \gamma} a^+(x-y)f(y,\gamma \setminus y)$$

$$f(y, \gamma \setminus y) = e^{-E^{\phi}(y, \gamma \setminus y)}$$

OPEN PROBLEM:

,

PRODUCES THE FECUNDITY AN EFFECTIVE REGULATION OF THE POPULATION?

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality

Ecological models with competition

Ecological models with establishment

Dieckmann-Law model Competition in economic models

Dieckmann-Law model

[Finkelshtein/Kondratiev, '08] (in preparation)

$$(LF)(\gamma) = \sum_{x \in \gamma} \left(m + \sum_{x' \in \gamma \setminus x} a^{-}(x - x') \right) \left[F(\gamma \setminus x) - F(\gamma) \right]$$

$$+\sum_{y\in\gamma}\int_{\mathbb{R}^d}a^+(x-y)\left(1+\sum_{y'\in\gamma\setminus y}b(y-y')\right)[F(\gamma\cup x)-F(\gamma)]dx$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment

Dieckmann-Law model

Competition in economic models

Dieckmann-Law model without competition

i)<u>DLM without local competition</u> $(a^{-} \equiv 0)$. Assume existence of corresponding MP $X_t \in \Gamma$. For $\Lambda \subset \mathbb{R}^d$ bounded put

$$n_t^{\Lambda} = \mathbb{E}(|X_t \cap \Lambda|)$$

Then $\exists t_0$:

$$n_t^{\Lambda} \to +\infty$$

 $t \rightarrow t_0 -$ (explosion).

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with ecompetition Ecological models with establishment

Dieckmann-Law model

Competition in economic models

Dieckmann-Law model: non-explosion

ii) DLM: non-explosion via competition $d \ge 2$ Construction of a Lyapunov functional (cf. [K/Skorokhod, '06]

$$e_{\delta}(x) = \frac{1}{1+|x|^{\delta}}, \ \delta > d$$

$$\Psi_{\delta}(x,y) = e_{\delta}(x)e_{\delta}(y)\frac{|x-y|+1}{|x-y|}\mathbb{1}_{\{x\neq y\}}$$

$$\mathbb{L}_{\delta}(\gamma) = \langle e_{\delta}, \gamma \rangle$$

$$\mathbb{E}_{\delta}(\gamma) = \sum_{\{x,y\} \subset \gamma} \Psi_{\delta}(x,y)$$

$$\mathbb{V}_{\delta}(\gamma) = \mathbb{L}_{\delta} + \mathbb{E}_{\delta}$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment

Dieckmann-Law model

Competition in economic models

Assume

$$a^+(x) \le \frac{A}{(1+|x|)^{2\delta}}$$

Introduce $A_{\delta} = AC(\delta, d) > 0$

Theorem

Assume

$$a^{-}(x) \ge 2A_{\delta}b(x)$$

 $\Rightarrow \exists C > 0:$

$$L\mathbb{V}_{\delta}(\gamma) \le C\mathbb{V}_{\delta}(\gamma)$$

If, additionally, $m \geq 2A_{\delta}\langle a^+ \rangle \Rightarrow$

$$L\mathbb{V}_{\delta}(\gamma) \le 0$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment

Dieckmann-Law model

Competition in economic models

Independent development with competition

 $b(x, \gamma) = z > 0$ (independent birth with constant intensity)

(i)
$$d(x, \gamma \setminus x) = e^{\beta E(x, \gamma \setminus x)} \Longrightarrow$$
 generator L^-
 $E(x, \gamma \setminus x) = \sum_{y \in \gamma \setminus x} \phi(x - y)$

(ii)
$$d(x, \gamma \setminus x) = m + \sum_{y \in \gamma \setminus x} a^{-}(x - y) \Longrightarrow$$
 generator L_m

(iii) $d(x, \gamma \setminus x) = \sum_{y \in \gamma \setminus x} a^{-}(x - y) \Longrightarrow$ generator L_0

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in Contact model in CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Direkmannal aw

model

Competition in economic models

(i) Glauber dynamics G^-

Symmetrizing measures for $L^- \ensuremath{ \ \ }$ are

grand canonical Gibbs measures $\mathcal{G}_{gc}(\beta,\phi,z)$

 $L^{-} \longmapsto X_{t} \in \Gamma$ equilibrium Glauber dynamics via the Dirichlet form method [K/Lytvynov, '05] Non-equilibrium GD:

[K/Kutovyi/Minlos,'07]

via CF evolution (see Lecture 2).

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models

Dieckmann-Law model

Competition in economic models

(ii) Surgailis process with competition

$$\begin{aligned} (L_m F)(\gamma) &= \\ \sum_{x \in \gamma} (m + \sum_{y \in \gamma \setminus x} a^-(x - y))(F(\gamma \setminus x) - F(\gamma)) + \\ z \int (F(\gamma \cup x) - F(\gamma)) dx \end{aligned}$$

Here we have a sub-Poissonian evolution of CFs.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models

with establishment

model

Competition in economic models

(iii) Stabilization via competition

[Finkelstein/K, 2007]

Consider (ii) with m=0 pure competition mechanism (i.e., without global regulation)

$$(L_0 F)(\gamma) = \sum_{x \in \gamma} \sum_{y \in \gamma \setminus x} a^- (x - y) (F(\gamma \setminus x) - F(\gamma)) +$$

 $z\int (F(\gamma\cup x)-F(\gamma))dx$

Hierarchical equations for CF <u>do not give</u> any a priori information about the density of the system. Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with motality Ecological models with competition Ecological models with establishment

Dieckmann-Law model

Competition in economic models

Mean density bound

Let $X_t \in \Gamma$ will be MP corresponding to L_0 and an initial measure with bounded density.

Let $\Lambda=B\left(0,R\right)$ be a ball with center at origin and radius R>0. Introduce the mean density

$$\rho_t^{\Lambda} := rac{1}{|\Lambda|} \int_{\Lambda} k_t^{(1)}(x) \, dx.$$

Our aim is to produce a time bound for this density and any such volume $\Lambda.$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematic Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment

model Competition in economic models

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models

Dieckmann-Law model

Competition in economic models

Spatially heterogeneous IBM

Theorem

Let a^- be a continuous function of positive type on \mathbb{R}^d .

Then the mean density

$$\rho_t^{\Lambda} := \frac{1}{|\Lambda|} \int_{\Lambda} k_t^{(1)}(x) \, dx$$

is uniformly bounded in t > 0 and Λ .

Comments

We use the explicit form of the generator instead of CF equation. Denote $\gamma_{\Lambda} = \gamma \cap \Lambda$. Then

$$L_0|\gamma_{\Lambda}| \le -\frac{C}{|\Lambda|}|\gamma_{\Lambda}|^2 + z|\Lambda|$$

That gives easily for $ho_t =
ho_t^{\Lambda}$

$$\frac{d}{dt}\rho_t \le z - C\rho_t^2.$$

The proof follows from an analysis of this differential inequality.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with catablishment Dieckmann-Law

Competition in economic models

General competition models in economics

$$b(x,\gamma) \equiv \lambda > 0.$$

Then

$$(LF)(\gamma) = \sum_{x \in \gamma} d(x, \gamma \setminus x) [F(\gamma \setminus x) - F(\gamma)] + \lambda \int_{\mathbb{R}^d} [F(\gamma \cup x) - F(\gamma)] dx.$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models

Dieckmann-Law model

Competition in economic models
Examples

1. Surgalis process

$$d(x, \gamma \setminus x) \equiv m > 0.$$

Invariant measure: Poisson measure with intensity $\frac{\lambda}{m}$.

2. G^- -dynamics

$$d(x, \gamma \setminus x) = \exp\left\{\sum_{y \in \gamma \setminus x} \phi(x - y)\right\}$$

Invariant measure: Gibbs measure, heuristically given by

$$d\mu_{\phi}(\gamma) = "\frac{1}{Z_{\phi}} \exp\left\{-\sum_{\{x,y\}\subset\gamma} \phi(x-y)\right\} d\pi_{\lambda}".$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law

Competition in economic models

Examples

3. "Linear part of G^- -dynamic"

$$d(x, \gamma \setminus x) = m + \sum_{y \in \gamma \setminus x} c(x - y), \quad m > 0, 0 \le c \in L^1(\mathbb{R}^d)$$

 $e^x = 1 + x + \dots$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models

Dieckmann-Law model

Competition in economic models

Examples

4. "Pure local competition model"

$$d(x, \gamma \setminus x) = \sum_{y \in \gamma \setminus x} c(x - y), \quad 0 \le c \in L^1(\mathbb{R}^d).$$

Hence,

$$(L_S F)(\gamma) = \sum_{x \in \gamma} \sum_{y \in \gamma \setminus x} c(x - y) [F(\gamma \setminus x) - F(\gamma)] + \lambda \int_{\mathbb{R}^d} [F(\gamma \cup x) - F(\gamma)] dx.$$
(3)

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law

Competition in economic models

Boundness of a density

Suppose that process \boldsymbol{X}_t exists. Define the first correlation function via

$$\mathbb{E}\Big[\sum_{x\in X_t(\cdot)}\varphi(x)\Big] = \int_{\mathbb{R}^d}\varphi(x)k_t^{(1)}(x)dx.$$

Theorem

Let $c \in L^1(\mathbb{R}^d)$ is a continuous function of positive type on \mathbb{R}^d . Then the function

$$\frac{1}{\Lambda|} \int_{\Lambda} k_t^{(1)}(x) dx$$

is uniformly bounded by t and Λ if its initial value is uniformly bounded by Λ .

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model

Competition in economic models

Let $\Lambda=B\left(0,R\right)$ be a ball with center at origin and radius R>0. Let h>0 and $\Lambda^h=\{x:\inf_{y\in\Lambda}|x-y|< h\}$. Then for h< R

$$\sigma(\Lambda, h) := \frac{\left|\Lambda^h \setminus \Lambda\right|}{\left|\Lambda\right|} = \frac{\left|\Lambda^h\right|}{\left|\Lambda\right|} - 1 = \frac{\left(R+h\right)^d}{R^d} - 1$$
$$= \left(1 + \frac{h}{R}\right)^d - 1 < 2^d - 1$$

By [Lewis et al.] for any $\eta:=\{x_k\}_{k=1}^n\subset\Lambda$

$$\sum_{k \neq j} c(x_k - x_j) = 2E_c(\eta) \ge \frac{n^2}{|\Lambda|} \frac{\left[\langle c \rangle - \delta(h)\right]^2}{\left[\langle c \rangle + \delta(h) + \sigma(\Lambda, h)\langle c \rangle\right]}$$

where

$$\delta(h) = 2 \int_{|x| > h} c(x) \, dx.$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

troduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law

Competition in economic models

Hence,

$$2E_{c}(\eta) \geq \frac{n^{2}}{|\Lambda|} \frac{\left[\langle c \rangle - \delta(h)\right]^{2}}{\left[\langle c \rangle + \delta(h) + (2^{d} - 1)\langle c \rangle\right]} \\ = \frac{n^{2}}{|\Lambda|} \frac{\left[\langle c \rangle - \delta(h)\right]^{2}}{\left[2^{d}\langle c \rangle + \delta(h)\right]}.$$

Set

$$C = C(h, d) := \frac{\left[\langle c \rangle - \delta(h)\right]^2}{2^d \langle c \rangle + \delta(h)} > 0$$

if only

$$\langle c \rangle - \delta(h) = \int_{|x| \le h} c(x) \, dx - \int_{|x| > h} c(x) \, dx \ne 0.$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in Contact model in CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with competition

model

Competition in economic models

Note that for $F\left(\gamma\right)=\sum_{x\in\gamma}\varphi(x)$

$$(L_{S}F)(\gamma) = -\sum_{x \in \gamma} \left(\sum_{y \in \gamma \setminus x} c(x-y) \right) \varphi(x) + \lambda \int_{\mathbb{R}^{d}} \varphi(x) \, dx.$$

Let $\varphi(x) = 1_{\Lambda}(x)$, $\Lambda \in B_c(\mathbb{R}^d)$. Then

$$L_{S}F)(\gamma) = -\sum_{x \in \gamma_{\Lambda}} \left(\sum_{y \in \gamma \setminus x} c(x-y)\right) + \lambda |\Lambda|$$
$$\leq -\sum_{x \in \gamma_{\Lambda}} \left(\sum_{y \in \gamma_{\Lambda} \setminus x} c(x-y)\right) + \lambda |\Lambda|$$
$$= -2E_{c}(\gamma_{\Lambda}) + \lambda |\Lambda| \leq -\frac{C}{|\Lambda|} |\gamma_{\Lambda}|^{2} + \lambda |\Lambda|$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law

Competition in economic models

.

Set

$$n_t^{\Lambda} = \mathbb{E}\left(|X_t \cap \Lambda|\right).$$

Then

$$\begin{split} \frac{d}{dt} n_t^{\Lambda} &= \mathbb{E} \left(L_S \left| X_t \cap \Lambda \right| \right) \\ &\leq \mathbb{E} \left(\lambda \left| \Lambda \right| - \frac{C}{\left| \Lambda \right|} \left| X_t \cap \Lambda \right|^2 \right) \\ &\leq \lambda \left| \Lambda \right| - \frac{C}{\left| \Lambda \right|} \left(\mathbb{E} \left(\left| X_t \cap \Lambda \right| \right) \right)^2 \\ &= \lambda \left| \Lambda \right| - \frac{C}{\left| \Lambda \right|} \left(n_t^{\Lambda} \right)^2. \end{split}$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment

Dieckmann-Law model

Competition in economic models

Since

 $n_t^{\Lambda} = \int_{\Lambda} k_t^{(1)}(x) \, dx$

we have for

$$\rho_t = \rho_t^{\Lambda} := \frac{1}{|\Lambda|} \int_{\Lambda} k_t^{(1)}(x) \, dx$$

that the following inequality holds

$$\frac{d}{dt}\rho_t \le \lambda - C\rho_t^2.$$

Therefore, if we consider Cauchy problem

$$\begin{cases} \frac{d}{dt}g(t) = \lambda - Cg^{2}(t) \\ g(0) = g_{0} \end{cases}$$

and $\rho_{0} \leq g_{0}$ then $\rho_{t} \leq g(t)$.

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment

Dieckmann-Law model

Competition in economic models

One has

$$\begin{split} \frac{\sqrt{C}dg\left(t\right)}{\sqrt{C}g\left(t\right)+\sqrt{\lambda}} &- \frac{\sqrt{C}dg\left(t\right)}{\sqrt{C}g\left(t\right)-\sqrt{\lambda}} = 2\sqrt{C\lambda}dt;\\ \ln \left|\frac{\left|\sqrt{C}g\left(t\right)+\sqrt{\lambda}\right|}{\left|\sqrt{C}g\left(t\right)-\sqrt{\lambda}\right|} - \ln \tilde{D} = 2\sqrt{c\lambda}t, \quad \tilde{D} > 0;\\ \frac{\sqrt{C}g\left(t\right)+\sqrt{\lambda}}{\sqrt{C}g\left(t\right)-\sqrt{\lambda}} &= De^{2\sqrt{c\lambda}t}, \quad D > 0;\\ \sqrt{C}g\left(t\right)+\sqrt{\lambda} &= De^{2\sqrt{C\lambda}t}\sqrt{C}g\left(t\right) - De^{2\sqrt{C\lambda}t}\sqrt{\lambda};\\ g\left(t\right) &= \frac{De^{2\sqrt{C\lambda}t}\sqrt{\lambda}+\sqrt{\lambda}}{De^{2\sqrt{C\lambda}t}\sqrt{C}-\sqrt{C}} = \sqrt{\frac{\lambda}{C}} \left(1 + \frac{2}{De^{2\sqrt{C\lambda}t}-1}\right) \end{split}$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with competition Ecological models with establishment

model Competition in

economic models Spatially

Then

$$g_0 = g\left(0\right) = \sqrt{\frac{\lambda}{C}} \left(1 + \frac{2}{D-1}\right).$$

Let g_0 be such that $D = 1 + \varepsilon$. Thus, if for any Λ

$$\rho_0^{\Lambda} = \rho_0 \le \sqrt{\frac{\lambda}{C}} \left(1 + \frac{2}{\varepsilon} \right)$$

one has that

$$\rho_t \leq \sqrt{\frac{\lambda}{C}} \left(1 + \frac{2}{(1+\varepsilon) e^{2\sqrt{C\lambda}t} - 1} \right).$$

Note that for $t \geq 0$

$$(1+\varepsilon)e^{2\sqrt{c\lambda}t} - 1 \ge \varepsilon > 0.$$

As a result, for any $\Lambda \in \mathcal{B}_c(\mathbb{R}^d)$

$$\rho_t^{\Lambda} = \rho_t \le \sqrt{\frac{\lambda}{C}} \left(1 + \frac{2}{\varepsilon} \right).$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment

Dieckmann-Law model

Competition in economic models

Heterogeneous Contact Models: random mortality

Lattice case: Joo/Lebowitz, Phys.Rev.E72, 2005

Mortality rate $m \to m(x, \omega) \ge 0$ Density evolution

$$\frac{\partial k_t(x)}{\partial t} = L^{a^+} k_t(x) - V(x)k_t(x)$$

where

$$L^{a^{+}}f(x) = \int a^{+}(x-y)[f(y) - f(x)]dy$$
$$V(x,\omega) = m(x,\omega) - \langle a^{+} \rangle$$

Parabolic Anderson problem for pure jump generator (CTRW in continuum)

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Random establishment

0

$$a^+(x-y) \to a^+(x-y)b(x,\omega)$$

Generator

$$(LF)(\gamma) = \sum_{x \in \gamma} m(x) [F(\gamma \setminus x) - F(\gamma)] +$$

$$\sum_{y \in \gamma} \int_{\mathbb{R}^d} a^+ (x - y) b(x, \omega) [F(\gamma \cup x) - F(\gamma)] dx$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Density evolution

$$\frac{\partial k_t(x)}{\partial t} = L_b^{a^+} k_t(x) - V(x)k_t(x)$$
$$L_b^{a^+} f(x) = b(x,\omega) \int a^+ (x-y)[f(y) - f(x)]dy$$
$$V(x,\omega) = w(x,\omega) \int a^+ (x-y)(x^+)$$

$$V(x,\omega) = m(x,\omega) - b(x,\omega)\langle a^+ \rangle$$

 $L_b^{a^+}$ is symmetric in

$$L^2(\mathbb{R}^d, b^{-1}(x)dx)$$

(quenched random measure?).

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Random fecundity

Random fecundity rate

$$\mathbb{R}^d \ni y \mapsto \varkappa(y,\omega) \ge 0$$

Birth rate

$$b(x,\gamma,\omega) = \sum_{y \in \gamma} a^+(x-y)\varkappa(y,\omega)$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductio

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki Aynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Density evolution

$$\frac{\partial k_t(x)}{\partial t} = L_{\varkappa}^{a^+} k_t(x) - V(x)k_t(x)$$

$$L^{a^+}_{\varkappa}f(x) = \int a^+(x-y)\varkappa(y,\omega)[f(y) - f(x)]dy$$

$$V(x,\omega) = m(x,\omega) - \langle a^+(x-\cdot)\varkappa(\cdot,\omega) \rangle$$

 $L^{a^+}_{\varkappa}$ is symmetric in

$$L^2(\mathbb{R}^d, \varkappa(x, \omega)dx)$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

CTRW in random environment

Two types of quenched jump generators:

$$L_b^{a^+} f(x) = b(x, \omega) \int a^+ (x - y) [f(y) - f(x)] dy$$

$$L_{\varkappa}^{a^+}f(x) = \int a^+(x-y)\varkappa(y,\omega)[f(y) - f(x)]dy$$

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

Feynman-Kac formula

Quenched CTRW:

$$L^{a^+,\omega}_{b,\varkappa} \to \xi^\omega_t$$

Density of population:

$$k_t(x) = \mathbb{E}_x[k_0(\xi_t^{\omega})e^{-\int_0^t V(\xi_s^{\omega})ds}]$$

Quenched vs. annealed

(cf., e.g., Donsker/Varadhan, Gaertner/Molchanov, Sznitman, ...)

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in geogenic models

Other aspects of IBM

multi-type systems
 (Finkelshtein/K; F/K/Skorokhod),

- mutation-selection models in genetics (K/Minlos/Pirogov; K/Kuna/Ohlerich)

– scaling limits (Finkelshtein/K/Kuna/Kutovyi; Finkelshtein/K/Lytvynov; Finkelshtein/K/Kutovyi) Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroductior

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in

 – Kawasaki dynamics in continuum (K/Lytvynov/Roeckner;K/Kuna/Oliveira/Streit)

plankton dynamics
 (K/Kutovyi/Struckmeier)

 stochastic evolutions in evolving random environments (Boldrighini/K/Minlos/Pellegrinotti; Struckmeier)

spectral analysis of Markov generators
 (K/Lytvynov; K/Minlos; K/Zhizhina; K/Kuna/Ohlerich)

Interacting Particle systems in Continuum: Continuous vs. Discrete

Yu. Kondratiev

ntroduction

Mathematica Framework

Glauber dynamics I: spectral gap

Glauber dynamics for Gibbs states

Spectral gap conditions

Glauber dynamics II: non-equilibrium case

Stochastic IBM

Free growth model Contact model in continuum CM with Kawasaki dynamics Free development with mortality Ecological models with competition Ecological models with establishment Dieckmann-Law model Competition in economic models